

amateur radio

Vol. 20, No. 3

MARCH, 1971

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FEDERAL COMMENT—MEMBERS

In recent months I have attended a number of meetings of Amateurs in various parts of Australia. I have usually been asked to speak on the present activities of our Federal body and in doing this I have referred to many of the difficulties that presently face us. One topic that has very often given rise to quite spirited discussion is whether or not we should be able to look to a significant increase in our membership and, if so, how this can be achieved.

You may recall that in the Federal Executive's report submitted to the last Federal Convention, a table was published showing the number of members as against the number of licensees in each State. As we have not yet received the membership figures from all of the Divisions as at 30th December, 1970, we as yet have been unable to up-date that table. However, this will be included in the Federal Executive report to be submitted to the next Federal Convention which will be held in Brisbane at Easter this year.

Australia-wide, as at 30th December, 1969, 54% of all licensees were members of the Institute. It is this figure that generally gives rise to extensive discussion. Of course, this figure must be treated with some caution. There are a certain number of people who retain their licence for many years but are in no way active. These people may have developed other interests or may retain the call sign allocated to them for only sentimental reasons. It is, I think, probably unreal to expect a 100% membership; the really difficult question is to determine what is a realistic percentage of licensees that the Institute can expect to be members. We know, for example, that the Radio Society of Great Britain has a membership of approximately 65%.

I would suggest that a 75% membership or even an 80% membership should be attainable. This figure would take into account all of those licensees who are really no longer interested, in a long term sense, in the hobby.

I do not think that we should disregard those who have temporarily other interests. If someone is contemplating coming back to the hobby, then he probably will have sufficient interest to remain or become a member.

The discussions I have heard on this topic have produced a number of suggested reasons as to why people are not members. It is worthwhile considering some of these suggestions as the reasons, if valid, may provide solutions.

There are, of course, some people who are "anti-Institute", either because of some incident in the past or because they do not know enough about the Institute and are proceeding on the basis of their own assumptions as to what the Institute is all about. There are, it is suggested, many people who are not members because, whilst not being "anti-Institute", they just did not know enough about what it is doing. Then, there are those people who are not members simply because they feel that the Institute cannot offer them anything worthwhile to justify their being members.

In a way, people falling into these various categories have something in common—a lack of knowledge of the fundamental role of the Institute to represent the Amateur Service. Perhaps even if the Institute offered nothing more than an effective medium to defend Amateur frequencies, many of these people would be prepared to become members.

But is it important that we seek more members? More and more of the Institute's resources and, therefore, its funds, are being directed to the representation and the defence of the position of Radio Amateurs. Our involvement in the I.A.R.U. Region 3 Association—which takes 20c per annum from each member's subscription—is because the Federal Council sees the importance of the attitudes of other administrations to the Amateur Service when questions of frequency allocation and regulation arise at an International level.

More and more, the Federal Executive is called upon to prepare detailed submissions in support of its position in its discussions with the Central Administration of the Postmaster-General's Department.

What results can the Institute show for which it is doing? I can now state that the proposals of the Australian Administration to the World Administrative Radio Conference Relating to Space Communications, which will com-

mence in Geneva in June this year, contain no proposal that affects either directly or consequently any Amateur frequency below 20 GHz.

In addition, the Australian Administration has adopted almost in toto the Wireless Institute's submissions in relation to the use of space by the Amateur Service and these proposals now form part of the Australian proposal.

If the Wireless Institute of Australia is successful in retaining, against pressure, any new privilege, this is to the benefit of not only our members but for the benefit of all Amateurs. To put it even more succinctly, Amateurs who take the benefit of what the Institute does, but do not, by being non-members, share the cost, make the cost greater for those who are members.

These facts have been highlighted by many of the discussions I have heard on this topic.

Usually the discussion has then turned to membership drives and other means of attracting new members. There are various things that can be done at a Divisional level though I believe that the best salesmen for membership are, in fact, the existing members. If each member made it his business to seek one new member in the forthcoming year, I am sure that we could see a significant change in our membership pattern, particularly in the three larger States of Queensland (in terms of size), New South Wales and Victoria, where the percentage of licensees as members is smallest.

There are, of course, other areas of the Institute's activities that can be improved and which will, if they are improved, make membership more attractive. For example, any improvement in this magazine should make the direct tangible benefits of membership more attractive. Have you any ideas? Let's hear them—perhaps write a letter to the Editor.

In the last resort though, it is our own enthusiasm as members that will attract more members. This magazine only goes to members, therefore it is going only to those people who already support the organisation. Can you support it now by finding another member?

MICHAEL J. OWEN, VK3KJ,
Federal President, W.I.A.

A Transistorised Carphone

PART ONE—THE RECEIVER

By L. B. JENKINS,† VK3ZBJ, and H. L. HEPBURN,‡ VK3AFQ

To a greater or less extent most readers will be aware that the engineering team working on the Australis Oscar project must, of necessity, be examining, selecting and using fairly advanced techniques. This and subsequent articles will attempt to show how some of the Australis work has been utilised to produce a fully transistorised f.m. carphone for the two metre nets.

INTRODUCTION

This article will describe the receiver portion of the complete transceiver and will be followed by a second article on the transmitter.

Fig. 1 gives the block schematic of the unit, whilst Figs. 2 and 3 give the appropriate circuit diagrams.

In the electrical design two i.f.s were used. The first i.f. is on 10.7 MHz. to allow use of freely available filters on this frequency and to be high enough to minimise image problems. The second i.f. is on 455 MHz, again to make use of freely available components.

Since the most likely end use for a transistorised f.m. receiver is in mobile systems, the h.t. supply was set at 12.5 volts and all design centred round this voltage. The unit will operate satisfactorily between 11.5 and 13.6 volts although, naturally, the transmitter output falls off at the lower figure.

Considerable attention has been paid to physical layout both from the con-

structional point of view and also with respect to ease of adjustment. Although the finished transceiver is small (the prototype is housed in a cabinet 4½" high x 10" wide x 10" deep) no attempt has been made to fully miniaturise it.

The complete receiver has been made on one p.c.b. 7½" x 4½", while the transmitter is made in three parts. The exciter/audio modulator is on a p.c.b. 1½" x 7½" and provides a 100 mW. f.m. modulated signal to the second p.c.b. which uses a Motorola 2N5589 to raise the power to some 1.2 watts. This stage in turn feeds a 2N5590 p.a. stage on a third p.c.b. to give a conservative 10 watts of output.

All p.c.b.s are mounted on a shallow "U" shaped aluminium sub-chassis with the receiver board in the bottom of the "U", the exciter board on one vertical side of it and the two power stages on the other vertical side. The front panel contains the speaker and the various operating controls. Fig. 4 gives the general layout of the boards and control components.

THE RECEIVER CONVERTER SECTION

The front end of the receiver uses two r.f. stages, the first a single neutralised TIS88 followed by a pair of TIS88s in a shunt cascode configuration. The choice of the shunt cascode was determined largely by the higher voltages per device that can be obtained. While a series cascode could have been used the roughly equal division of the available 12-13 volts supply would have meant that each device would only have about 6 volts of supply, a condition not conducive to the best results from FETs.

Double tuned circuits are used between the first and second r.f. stages and again between the second r.f. stage and the mixer. This method of coupling has been used to achieve an adequate band pass for use on the f.m. nets centred on 146 MHz., although there is no reason why the converter could not be centred on, say, 144.5 MHz. for a.m. work. In this case a normal tunable i.f. would be necessary.

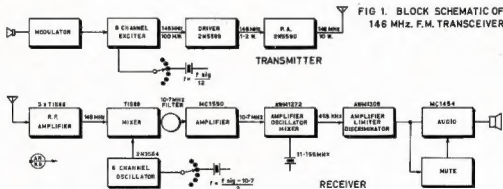


FIG. 1. BLOCK SCHEMATIC OF 146 MHz. F.M. TRANSCEIVER

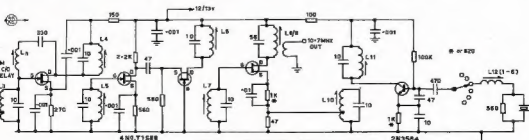


FIG. 2. RECEIVER CONVERTER

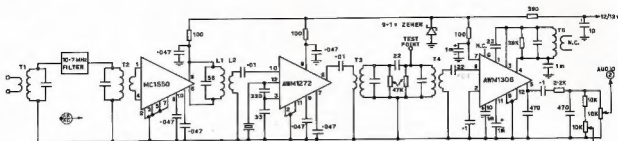


FIG. 3A.

INTERMEDIATE FREQUENCY STRIP

AUDIO

The mixer is a single TIS88 using low impedance injection from the oscillator into the source.

No dramatically new techniques have been used in the converter section of the receiver, but the resultant high performance and ease of alignment has been achieved only after much detail work on layout and circuit constants. The need to go through this (quite frustrating!) phase of development underlines the often forgotten maxim that at v.h.f. the circuit diagram alone is not a guarantee of success.

The six-band oscillator section is about as simple as it can be. A single 2N3564 uses third overtone crystals in the 45 MHz. range and triples into the collector tuned load. A second tuned circuit $\frac{1}{2}$ away from the collector tank cleans up the injection waveform and is tapped to provide impedance transformation into the mixer source. Adequate injection voltage is available.

Crystal switching uses the tried and true rotary switch. Considerable work was done on a diode switching system, but it did not prove to be completely reliable under service conditions. The reasons for this are not fully known, but appeared to be tied up with the small (but finite and variable) resistance of the diode in its switched-on condition.

THE RECEIVER I.F. SYSTEM

It is in this part of the receiver that the most interesting technical developments have been used.

Input from the converter at 10.7 MHz. is applied to a Toyo Type 10M2A1 filter having a 3 dB. bandwidth of 30 KHz. and a passband ripple of less than 2 dB. Narrower filters were tried, but it was found that off-frequency and/or over-deviated stations were unintelligible. Note that the filter input and output transformers are supplied with the filter and are essential to its proper performance. The bandpass and shape of the passband on the four filters so far tried have been very close indeed to the individual calibration sheets supplied with each filter.

Output from the second filter transformer at low impedance is amplified in a conventional MC1550 stage whose output feeds an AWM1272 oscillator/amplifier/mixer device. This device is made by A.W.V. and has only recently become available.

Fig. 5 gives the internal circuitry of the 1272. It contains two Clapp type oscillators (only one of which is used

in the receiver under discussion) and an emitter coupled balanced mixer. This one device has replaced the large number of discrete components used in some of the earlier experimental work.

Using a 10.7 MHz. input and a heterodyning crystal on 11.155 MHz. (or 10.245—it makes no difference) the output of the 1272 is on 455 KHz. Two standard Rapar miniature transistor i.f. transformers are used back to back to couple output into the AWM1306 stage. The two transformers are top coupled and resistively loaded to give optimum bandpass.

The 1306 is another multipurpose A.W.V. microcircuit. Its configuration and mode of operation were described in an excellent article by John Reynolds, VK3ZMU, in the June 1970 issue of "A.R."

Essentially the 1306 acts as an amplifier, a limiter and a quadrature detector and gives two audio outputs. In the Australls circuitry the second audio output is used to give a.f.c. and mute, but in the current design, a.f.c. is not used and a very simple mute circuit has been adopted.

The whole i.f./detector strip is run from a 9-volt zenered rail.

AUDIO AND MUTE

The audio section proper consists of a Motorola MC1454 IC to give a watt of output with an 8 ohm speaker. A very simple 2N3565 pre-amplifier is used to give some audio lift.

Muting is obtained as follows. Audio output from the 1306 is taken to the "tops" of two parallel 10K potentiometers. One of these potentiometers acts as a normal volume control and feeds the audio pre-amplifier (Audio 1). The slider of the second potentiometer, the mute control, is taken to a second pre-amplifier (Audio 2) whose coupling capacitors emphasise the higher audio components. Amplified output from

this stage is rectified and the resultant d.c. applied to the base of a third 2N3565. The collector of this transistor is connected to pin 4 of the 1454 via a 10K resistor.

With the mute control in the off position no d.c. is applied to the base of the 2N3565 switch and pin 4 of the 1454 is at its normal working level. As audio noise is applied to the pre-amplifier and rectified, the 2N3565 switch approaches the "on" stage. When "on" pin 4 of the 1454 is pulled down towards earth potential and cuts off the IC.

Some delay time is achieved by means of the 1.0 μ F. capacitor immediately following the AN2001 noise rectifier.

GENERAL

The receiver as described has been in one writer's vehicle for a long shake-down period. While the signal generator says that the mute will open with less than 0.3 microvolt of input, the effect of this sort of sensitivity is only really apparent when used mobile over a long period of time under a wide variety of circumstances and over many different routes.

Suffice it to say that on the most used route (to work and back!) copy has been consistently made from all parts of Melbourne when modified commercial units (both valve and transistor) have heard only noise.

Since the converter part of the receiver is that to be used in the next satellite for reception of 2 metre f.m. signals, the performance obtained augurs well for the future.

With the exception of two ICs, the p.c.b's, the filter and of course the crystal, no special components are needed and in fact those used were obtained ex stock through the VKS W.I.A. components service.

Much interest has been shown in the development of this receiver and many

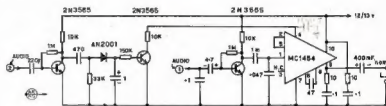


FIG. 3B. AUDIO AND MUTE

Modification to the Mute Circuit of the Pye Mk. 2

RODNEY D. CHAMPNESS,* VK3UG

The original muting circuit of the Pye Mk. 2 v.h.f. a.m. transceiver leaves much to be desired in its method of operation as undoubtedly owners of this particular model have found out. The trouble comes about through the use of a relay to switch the speaker on and off. It is a well known fact that a relay requires a much higher current to pull it in than to drop it out. In other words, the relay may require 10 mA. to pull it in, but the current may have to drop to 5 mA. before it drops out again, which actually means in the case of the Pye Reporter that the muting must be much harder than desirable, causing weak signals to be missed, for the convenience of having muting during no-signal times. This used to cause me to miss many of the weaker signals, much to my annoyance.

Having put up with this defect for some time, I decided some form of fully electronic mute was most desirable. I came across the circuit that follows in an American magazine. I have modified it slightly so that it will suit the Pye. The original circuit required no extra valves, but this can only be so when the set has simple a.g.c. or only a slightly delayed a.g.c. system. The original circuit used the variation in the screen voltage of one of the a.g.c. controlled r.f. or i.f. stages, as shown in the second diagram, to operate the muting circuit. I won't describe the original American circuit, just the one suitable for the Mk. 2—it will suit, of course, the Mk. 1 and Mk. 3 with the addition of a small triode such as a 6C4.

To convert the Mk. 2, first of all, get rash and remove all the muting circuit, including the relay, wiring the speaker line direct from the transformer to the speaker. Having done all these drastic alterations, you will

now find you have quite a bit of space about the 12AT7 socket. Just wire it as per circuit diagram and away it should go.

The principle of operation is quite simple. With no signal input, V1 will have no bias and will be conducting as much as it is able, the 100K (R6) restricting the total current to a quite reasonable level. As a result of this, the anode of the OA202 will be negative in respect to the cathode and it will be cut off, which means that it is an effective switch between C3 and C4 so the set is effectively muted, providing of course that VRI is set so that this condition does apply.

Should your valve be a bit different to mine, R4 and R7 can be juggled to get a voltage at the earthy end of VRI, which is slightly less positive than the voltage at the plate of the valve. This will mean that the diode is conducting and the set is unmuted as the diode will act as a small series resistor between C3 and C4. As the slider on VRI is advanced towards the positive un-earthed end, the diode will become reverse biased and the set muted.

When a signal comes in, a negative bias is developed across the detector load and this is applied to the grid of V1 causing it to gradually cut off which means that depending on the setting of VRI the set will unmute at a set pre-determined signal level. It might be noted that the set can be made to unmute on signals which have not even actuated the d.a.g.c. I can hear signals now that I couldn't previously and the mute closes quickly and positively after every received transmission.

You may think that R1, R2, C1 and C2 are unessential for this job, but I can assure you that this is not so. The 12AT7 will act quite effectively as an audio valve and cause the diode to open and close at an audio rate. Mostly this caused the residual noise to leak through, in fact, all the noise that the noise limiter removes is being amplified by this cir-

cuit as it comes before the noise limiter. These four components are used as an audio filter so that only pure d.c. is supplied to the 12AT7.

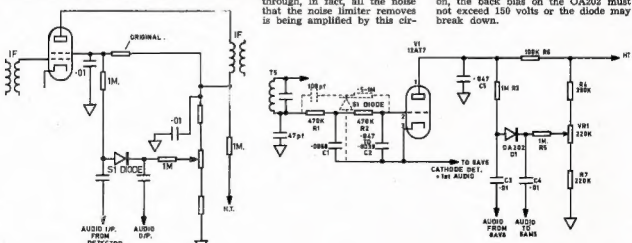
C5 is optional and is inserted to back up the aforementioned components to suppress audio leakage.

There is only one defect with this circuit that I have noted which should be able to be corrected. This defect is that if there is a quite high noise level, say ignition, etc., the mute will open, giving you a large dose of noise that can be well done without. I have thought of an addition to this circuit which may work. It consists of a small value capacitor of a 100 pF. or thereabouts possibly, followed by a diode and a series resistor as shown on the diagram dotted in. The theory behind this being that the noise pulses are much higher in frequency than the average audio. These are rectified in this circuit and applied to the grid of the 12AT7 to hold it fully conducting to counteract the negative voltage developed by the audio detector. The values of this addition would need to be played with to get the desired effect.

I have used this mute circuit on a couple of sets and in both, the result has been very successful and I feel I can recommend it. It would undoubtedly be quite suitable to use in other valved a.m. equipment, h.f. or v.h.f. This mute does not give an entirely quiet receiver as there is still a small amount of high frequency audio leakage across the capacity of the diode, but this is of such a low amount that it is of no consequence.

The value of C2 can be varied quite a bit to give slower response to incoming signals and particularly noise pulses. A suggested upper value could be about 0.047 μ F.

One precaution: With the mute hard on, the back bias on the OA202 must not exceed 150 volts or the diode may break down.



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Australis-Oscar 5 Spacecraft Performance*

By JAN A. KING, W3GEY

In the rather brief lifetime of the Australis-Oscar 5 experiment a number of useful experimental and operational results have been achieved. The satellite was launched on 23rd January, 1976. As of this writing, 211 formal reports have been received from 27 countries around the world on both telemetry and propagation results. Many other stations were known to have received the satellite, but did not submit quantitative data.

Based on reports received, here is a summary of the performance of each system on the AO-5 spacecraft:

THERMAL BEHAVIOUR OF AO-5

The temperature of AO-5 at ejection from the second stage of the Delta vehicle was 20°C. despite its proximity to the second stage engine and a very cold nitrogen gas jet during launch. The temperature, however, began to rise during orbits 1 through 10 and then stabilised internally at 43°C. $\pm 3^\circ\text{C}$, where it remained for the duration of the satellite's useful life. This temperature is fairly high, although it is within the design temperature range of 19° to 45°C. The effects of this higher temperature were, unfortunately, all adverse. Battery lifetime was somewhat shortened during the initial phase of discharge; but worse than this, the 144.05 MHz beacon power dropped off faster with decreasing supply voltage due to the decreased efficiency of the r.f. power output transistor.

External temperature measurements were higher in sunlight and cooler during eclipse periods as observed by many reporting stations. As the spacecraft entered the dark portion of the orbit the skin temperature dropped from its 55°C average to 42°C. $\pm 3^\circ\text{C}$. The internal temperature, however, remained fairly constant, dropping only two to three degrees during the entire eclipse period. Acknowledgment is due to Bill Armstrong, W0PG, John Fox, W0LER, Natar, K2SS, and others for their data in this area.

The spin rate about the X-axis in later orbits became quite slow so that the skin sensor located on the +Y surface showed changes in temperature as parts of the satellite rotated in and out of its own shadow. This data was most useful in determining the roll rate about the stabilised axis of the spacecraft. John Goode, W5CAY, reported this data for many orbits between 100 and 250. Skin temperature data indicated a spin period of 7 to 8 minutes about the X-axis after the initial 100 orbits. An example of this data is shown in Fig. 1 for orbits 168, 205 and 206, along with horizon sensor data.¹

THE AO-5 POWER SYSTEM

The spacecraft battery voltage decreased with time faster than predicted by pre-launch testing of individual cells (see Fig. 2).² It is now known that

the accelerated battery discharge was caused by two factors. First, the higher satellite temperature accelerated the normal chemical reaction in the alkaline-manganese batteries. Secondly, an additional 18 mA. of current was attributed to a failure of the 10 metre modulator that occurred on orbit 3. It was verified that the 18 mA. was independent of the ten metre transmitter itself by commanding the transmitter off and observing that the extra current was still

present. The ten metre modulation failure has also been attributed to the higher spacecraft temperature.

MAGNETIC ATTITUDE STABILISATION SYSTEM AND HORIZON SENSORS

One of the best operating systems on board the satellite was not electronic in nature. The Magnetic Attitude Stabilisation System (MASS) functioned more efficiently than some of us had anticipated. Early reports indicated that antenna nulls were occurring on the 144.05 MHz signal once every 16 seconds, making telemetry decoding very difficult. By orbit 100, signal fades had reduced to one or two per station pass (approximately 20 minutes in duration). To the Amateur using the spacecraft this is a significant improvement over past satellites in the Oscar series and should prove to be a valuable tool in future Amateur spacecraft to achieve the continuous reception of a down-link signal.

The three orthogonal earth or horizon sensors used in the spacecraft were 2N2452 photo-transistors operated in a diode mode, having a spectral response between 5,000 and 10,500 Å.³ Each sensor's field of view had been stopped to 5 degrees by a small collimation tube. A photometric calibration of these sensors was, unfortunately, not undertaken due to the shortage of time in the test schedule. While the original design of this part of the telemetry system was to give an on-off indication when looking toward or away from the bright earth, the devices were found to be more sensitive and capable of detecting the decreasing brightness of the earth's atmosphere as the sensors viewed the earth-to-space transition.

When viewing the bright earth the telemetry output indication was approximately 1450 Hz. and during the transition the telemetry frequency gradually decreased to a dark condition of 600 Hz.

Amateurs using a fast discriminator to decode the modulation observed, during periods of good signal strength, small variations in the frequencies of the telemetry tones as the sensors swept across the earth's disc. These were attributed to cloud formations.

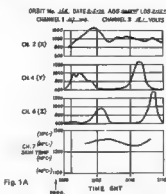


Fig. 1A

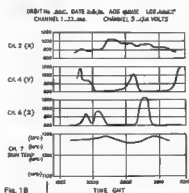


Fig. 1B

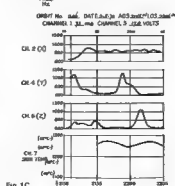


Fig. 1C

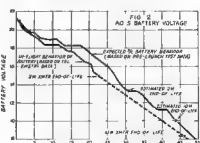


Fig. 2.

* Reprinted from "QST," December 1976.

Two examples of this data are shown in Fig. 3.

With a discriminator of this type, the Goodard Amateur Radio Club, WA-3NAN, decoded telemetry information for all the passes received. Fig. 4 shows horizon sensor information for various passes. Each frame shows the maximum rate of change of brightness observed on any of the sensors during a given pass. During orbit 4 the maximum observed rate of frequency change was found to be 700 Hz. per second, while pass 182 exhibited a maximum rate of change of only 10 Hz. per second. This is indicative of the reduced spin rate of the satellite.

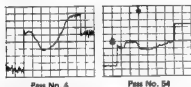


Fig. 3.—Two examples of variations in the plus-Y sensor output due to variations in the earth's brightness. Note the sudden increase and decrease in intensity during the frame from pass 54. This is thought to be due to the sensor sweeping across a bright cloud region. Time divisions are 1 sec.

During daytime ascending nodes, after the spacecraft had stabilised, a regular sensor pattern was observed. WSCAY demonstrated this data most effectively (see again Fig. 1). The X-axis shows no true periodic nature, but rather a gradual transition followed by small variations about an average 'light' condition. The Y and Z sensors show a periodic behaviour characteristic of the satellite's roll rate about the stabilised X-axis. The skin temperature shows a cyclic variation as the +Y face rotated in and out of the spacecraft's own shadow. Of particular significance is to observe that the Z sensor always lags behind the Y sensor (approximately two minutes) in detecting the earth. With the +X-axis pointing north as the satellite crossed the equator, the spacecraft spin was thus clockwise as observed from the north pole of the earth.

The maxima in the external temperature curve were (within experimental error) out of phase with the +Y sensor. Since the T_{ext} thermistor was located on the +Y face, then the temperature was a minimum during times when the +Y face was viewing the earth. This is, in fact, the time when the +Y face should have been in shadow.

As the spacecraft travelled north from the equator the +X-axis should have begun to dip toward the earth as the strong dipole moment of the satellite (11,800 pole-cm) followed the local geomagnetic field vector which caused it to rotate twice per orbit (see Fig. 5). WSCAY's data showed that the +X-axis sensor did begin to gradually come on shortly after his signal acquisition time over a period of several minutes. This is precisely what one would have predicted as the +X sensor looked deeper into the earth's atmosphere which reflected more and more scattered light into the sensor.

Region	Stations Reporting Useful Data	Stations Reporting Telemetry >50% of Passes	Stations Reporting Telemetry <50% of Passes
1	66	52%	48%
2	114	32%	68%
3	31	45%	55%

Table 1.

The average roll period observed in this data is 7.5 min. This is thought to be the degree of stabilisation that persisted until the termination of the satellite's active life. The effectiveness of this system is best evaluated in terms of the very large reduction in the signal fading rate due to antenna nulls. This, in turn, implies an overall reduction in the loss of spacecraft data. For a satellite in the Amateur Radio Service it is apparent that this method of stabilisation is most effective and very easily implemented.

THE AO-5 COMMAND SYSTEM

A telecommand link on two metres was utilised to turn on and off the ten metre beacon transmitter in an effort to conserve the spacecraft's power supply. An a.m. tone modulation technique was employed. The ten metre

beacon which consumed 0.8w of power, was to be commanded on during weekends when a maximum number of users was anticipated.

Prior to launch, considerable difficulty was encountered with the spacecraft command receiver due to in-band interference from the 144.05 MHz. beacon transmitter. It was only possible to eliminate the interference by adding a steep skirted bandpass filter centered at the command frequency. This filter gave 50 dB. of rejection at the beacon frequency, but unfortunately had a relatively high insertion loss when placed in front of the receiver. The result was that the command receiver required a signal of -76 dBm. (35.4 μ V.) under ambient (room) conditions to decode a command. This, to be sure, was considered marginal performance.

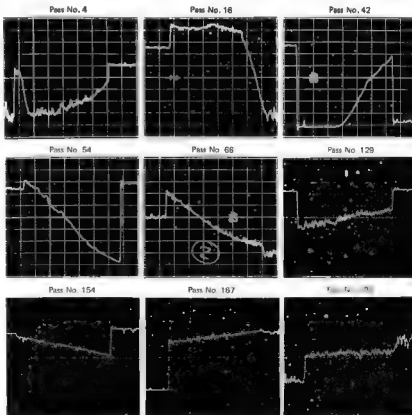


Fig. 4.—The maximum rate of change of the horizon sensors during limb transit on for various passes of AO-5. The data shows a damping factor of 70 in only 13 days. This is a particularly graphic demonstration of the effectiveness of the stabilisation system. Time divisions are 1 sec.

The problem was further complicated by a detuning of the second i.f. stage that occurred during tests under vacuum conditions. This problem could not be traced to a single component in a timely fashion so it was decided to peak the receiver for maximum sensitivity under vacuum conditions. When the receiver was again tested under vacuum conditions the sensitivity was observed to be 10 dB better. Thus, it was expected that the in-flight sensitivity would improve some 10 dB over its ambient condition, giving a final sensitivity figure required to operate the decoder of -88 dBm. The spacecraft was launched with the receiver in this condition.

Fig. 8 shows a plot of the spacecraft total current during the entire lifetime of the two metre beacon, when telemetry data could be obtained.* From this data it is clear when commanding occurred and the status of the ten metre beacon during the lifetime of the satellite.

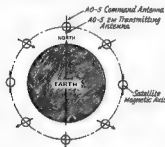


Fig. 8.—Motion of a magnetically oriented satellite in a polar orbit.

Table 3 lists the command transmitter schedule, indicating the successfully transmitted commands and the effective radiated power used to execute the command. Although early command attempts were unsuccessful, after orbit 72 it became increasingly less difficult to achieve a successful command and it became possible to maintain the week-end-only operation schedule for the ten metre beacon as originally planned. It is felt that the increased overall sensitivity of the command system was due to a combination of factors:

- Spacecraft command antenna orientation favourability (particularly over Australia, due to the effectiveness of the magnetic attitude stabilisation system).
- Reduction of the interfering signal level (144.05 MHz.) as the battery voltage (and hence the power of the beacon) decreased.
- Stabilisation of the command receiver temperature and pressure which improved the sensitivity of the receiver.

The effectiveness of the command system, particularly despite the receiver problems, is of particular significance to future Amateur space experiments. It not only demonstrated, for the first time in an Amateur satellite, the effectiveness of ground command as a means of switching various experiments on and off, but of greater

significance, it represents an effective means of controlling Amateur spacecraft emissions so as to prevent interference to other services who may share the Amateur bands. This should help assure the continuing usage of Amateur space experiments without the need for power flux limitations imposed on the satellite down-link signal.

SPACECRAFT LIFETIME

As previously indicated, the failure of the ten metre modulator is considered responsible for the increased battery current drain of 18 mA. This additional current drain shortened the lifetime of the satellite. The two metre beacon could be received through approximately orbit 280 on the 23rd day after launch. The ten metre beacon was turned on by command on orbit 281 and was left on continuously until it reached end of life around orbit 580 on the 46th day after launch. The difference in beacon lifetimes is due to the variation in cut-off voltage for the transmitters. The two metre transmitter power output went to zero very rapidly at a supply voltage of 15V, while a significant output could be obtained from the ten metre transmitter even at voltages as low as ten volts. While the spacecraft lifetime on two metres was shorter than the design lifetime of thirty days, a significant quantity of telemetry data was obtained never the less.

THE NATURE AND RELIABILITY OF AMATEUR REPORTS

An additional feature of the AO-5 experiment was the opportunity to evaluate the performance of Amateurs

in reporting scientific-type data. After allowing several months to be certain that all late reports had been received, an effort was made to determine what type of information Amateurs were most interested in reporting and approximately how much variation in measurement occurred from station to station.

It was decided to report on the results by I.T.U. regions since different satellite passes were common to these regions, i.e. Region 1 (Europe and Africa) could generally not hear the same passes as Region 2 (North and South America) and so forth. Table 1 lists the number of useful reports received from each region and those which did and did not contain telemetry information. We may infer that stations not reporting telemetry results were primarily interested in other aspects of the experiment or in phenomena such as Doppler measurement. (Only the telemetry results are covered in this report since they were the primary indicator of the spacecraft performance. Another report prepared by Raphael Solter, K2QBW, gives a detailed presentation of the ionospheric propagation results of AO-5.)

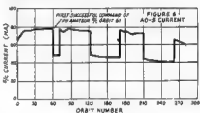


Fig. 8.

Table 1 indicates that, on a percentage basis, Region 1 and Region 3 participated more actively in the telemetry decoding activities. This is somewhat surprising, since it was anticipated that U.S. Amateurs would be suitably equipped to make telemetry measurements.

It was of interest to determine the variation in measured values from as many stations as possible during a single pass. Variation in spacecraft parameters for a short period when the satellite passed over a given region, was thought to be quite small (except for skin temperature variation) during daylight passes. The variation in data from reporting stations, then, can be primarily considered as individual station measurement error. In each region a particular pass was chosen for which a maximum number of reports was received.

Table 2 shows data for each station reporting and the range in data as well as the maximum percent. of error from the median value. The error observed for the spacecraft battery voltage shows the lowest error due to the relatively "flat" nature of the voltage-to-frequency conversion curve and the fact that most of those reporting rounded off the reported measurement (as called for by the telemetry reporting form). Certain stations (those underlined) were used as control stations for each region since they were known to have better than average decoding equipment.

Region I Pass 51				
Call Sign	Channel 1 (f.m.k.)	Channel 3 V (volts)	Channel 5 Tst (C/U)	Channel 7 Tst (C/U)
GLADE 72	19.4	18	49	
FIDC	19	4.3	55	
HBVBS 73	19.0	62.5	47	
AO Values 8	0.6	5.5	5.0	
Max 9				
Error				
Median	1.3%	1.3%	0.8%	7.0%
(Low/High) data from Station 5. Telemetry reports have not yet been received.				
Region III Pass 17				
WADDF 78	20.2	94.8	51	
K238	19.1	68	54	
WABHAT 78	19.8	45	54	
WELF 78	20.5	45	52	
W5CAY 77	20	—	53	
W3GER 78	20	—	52	
W3GRC 78	20	51	—	
KACG 76	20.4	45	53	
W4AGCS 76	20	43	47	
W3GAL 76	20	48	53	
W1AIM 78	20	40	—	
K0YB 76	20	44	53	
K2JAB 78	20	—	51	
K1NTV 79	20	46	49	
W3HM 82	20	49	49	
AO Values 13	0.7	9	11	
Max 9				
Error				
Median	7.0%	1.7%	9.0%	10%
Region III Pass 21				
V4LXN 78	20	45	40	
TLJWB 80	20	46	46	
V4LXV 79	20	42	46	
ZLJSTN 76	20	42	47	
V4LXN 79	20	45	45	
ZLJSTN 75	20	44	44	
V4LXN 78	20	42	46	
V4LXN 78	20	43	46	
AO Values 18	0	4	4	
Max 9				
Error				
Median	6.7%	0%	4.7%	4.3%

Table 2.

All regions show comparable data error. The magnitude of the error (less than 10% max.) was approximately the error estimated prior to the launch. This data does not utilise more powerful statistical methods that could be used to more accurately evaluate the data (i.e. a uniform probability density was assumed for all data). The maximum error figure of 10% does indicate that Amateurs throughout the world are capable of making significant data measurements with considerable accuracy.

SUMMARY

With the exception of a failure in the modulator of the ten metre beacon transmitter, all Australis-Oscar 5 mission objectives were met:

- The spacecraft was effectively stabilised to two revolutions per orbit (geometric alignment) within the lifetime of the satellite.
- Reliable Amateur spacecraft telecommand was demonstrated.
- The effectiveness of the seven channel telemetry system was verified. Amateur data generally showed less than $\pm 10\%$ variation from median values.
- Significant results were obtained on propagation effects over the satellite-to-earth link in the ten metre band.

(e) Partial success was obtained in achieving the design lifetime of several weeks for both spacecraft transmitters using only chemical batteries.

While the response to AO-5 was gratifying (many stations reported it to be the most interesting Amateur space activity to date) it does not compare with the level of excitement that was generated by the repeater satellites such as Oscar III. AMSAT is presently planning a next generation of Oscars. These satellites will carry two repeaters and an r.t.t.y. telemetry system capable of measuring as many as 60 parameters. The design lifetime of these satellites will be one year, using a solar cell power source. Whether you are interested in r.t.t.y., f.m., a.m., s.b., DX traffic handling, or even contesting there are activities and special experiments being planned for you with Oscar 6. If you are interested in finding out how you can contribute to this new and exciting chapter in Amateur Radio write: AMSAT, P.O. Box 27, Washington, D.C., 20044, U.S.A.

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"CQ" W.W. W.P.X. S.S.B. CONTEST, 1971

PRECIS OF RULES

Date 27th/28th March.
Time Start 0000GMT Saturday, finish 2400 GMT Sunday. Only 30 hours out of the 48 hours are permitted for single operator working. The 18 hours of rest may be taken in up to three periods during the contest and such periods must be logged.
Bands: 1.8 to 30 MHz.
Mode: Two-way s.b. only.
Exchange: RS report plus three digit contest number commencing with 001.

Scoring QSO Points—
1.8 to 7 14 to 28
MHz, inc. MHz, inc.
Between stations on different continents — 1 3
Between stations in the same continent but in different countries — 2 1

QSO between stations in the same continent and in the same country are permitted for multiplier purposes only.

Multiplier: Determined by the number of different prefixes worked. A prefix is considered to be the two or three letter/number combination which forms the first part of an Amateur call, e.g. W1, K1, WA1, 6X6, 4Z6. Each prefix may be counted only once during the test.

Total: Single operator, single band—QSO points multiplied by the number of different prefixes worked; single operator, all band—total QSO points from all bands multiplied by total number of different prefixes worked. N.B.—A station may be worked once on each band for QSO point credit. However, prefix credit can be taken only once regardless of the band.

Awards: In each category for each call area of Australia. To be eligible for a single band award the log must contain a minimum of 15 hours of operation.

Log entry: Logs to be postmarked no later than 1st May, 1971, and addressed to "CQ" W.P.X. S.S.B. Contest Committee, 14 Vanderventer Ave., Port Washington, Long Island, N.Y., U.S.A., 11050.

Note: Complete rules are published in recent issues of "CQ" magazine.

PROVISIONAL SUNSPOT NUMBERS

DECEMBER 1970

Dependent on observations at Zurich Observatory and its stations in Locarno and Arosa.

Day	R	Day	R
1	85	15	88
2	88	16	88
3	75	17	70
4	65	18	88
5	85	19	88
6	85	20	101
7	75	21	88
8	88	22	90
9	87	23	78
10	87	24	83
11	88	25	88
12	87	26	81
13	85	27	50
14	88	28	47
15	83	29	50
16	81	30	71
		31	85

Mean equals 76.6

Smoothed Mean for June 1970: 105.1

Predictions of the Smoothed Monthly Sunspot Numbers

January 85	April 78
February 83	May 77
March 81	June 75

Swiss Federal Observatory, Zurich.

Command Number	Station E.R.P.	Station Commanding	Date	Orbit Number	Purpose of the Command (Other Comments)
1	10 KW.	WA1IOX (U.S.A.)	1/28	81	10M Beacon off (first command of Amateur S/C)
2	20 KW.	VK3ZBJ (Aust.)	1/29	72	10M Beacon on
3	10 KW.	VK3ZBJ (Aust.)	1/31	97	Command Receiver Freq. Check (Beacon off, on; off, on)
4	20 KW.	VK3ZBJ (Aust.)	2/2	123	10M Beacon off (routine)
5	10 KW.	VK3ZBJ (Aust.)	2/6	172	10M Beacon on (routine)
6	10 KW.	VK3ZBJ (Aust.)	2/9	210	10M Beacon off (routine)
8	20 KW.	VK3ZBJ (Aust.)	2/13	260	10M Beacon on (last command during S/C lifetime)

Table 3.

CHOOSE THE BEST—IT COSTS NO MORE



O. T. LEMPRIERE & CO. LTD. Head Office: 31-45 Bowdoin St., Alexandria, N.S.W., 2015 and at Melbourne — Brisbane — Adelaide — Perth — Newcastle

SOLID STATE CONVERSION OF THE G.D.O.*

Circuits for modernising your Grid-Dip Osc. to obtain greater flexibility and sensitivity

PETER A. LOVELOCK, W6AJZ

The grid-dip oscillator is one of the most useful items of test equipment to have around the Amateur station. The main short-coming of most tube-type g.d.o.'s is their requirement for a.c. power. This is no problem at the workbench, but it is a definite limitation for portable or mobile work. Anyone who has used a g.d.o. to tune an antenna knows what a chore it can be to run an a.c. power extension line up a tower—not to mention the safety hazard.

Today's catalogues offer a selection of solid state "dippers" in an attractive price range. They have the advantage of being usable anywhere. If you already have an older g.d.o., you may have considered trading it in for one of the contemporary models, or maybe even building a solid state unit from scratch.

A simpler and much cheaper solution is to convert your tube g.d.o. to a solid state circuit. If you are reluctant about tearing into a commercially built unit or kit—don't be. The conversion task is simple, painless, and can be done in an evening. The result will give you the performance and flexibility of the latest models at a fraction of the cost.

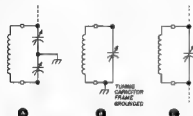


Fig. 1—Types of tuned circuits used in g.d.o.'s. Split-tank is shown in A; parallel-grounded and parallel ungrounded versions in B and C.

THE TUNED CIRCUIT

Before you reach for the soldering iron, inspect your tube-type g.d.o.'s schematic. The tuned circuit will influence your decision on the solid state circuit to use. You'll want to keep the tuned circuit intact as well as the dial calibration. Thus, you won't have to change your plug-in coils.

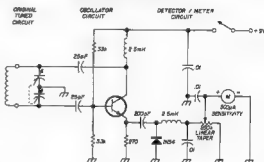
The g.d.o. is nothing more than a simple oscillator. In tube types, the rectified grid current is measured on a meter to indicate a "dip" when power is absorbed from a nearby resonant circuit. Solid state devices don't give grids, or course, so an indication on a solid state g.d.o.'s meter is obtained from the oscillator's rectified output. The basic operating principle is the same in both circuits.

Common tuned tank circuits used in commercially built g.d.o.'s are shown in Fig. 1. Your schematic will show if your unit has a split-capacitor,

parallel-grounded, or parallel-ungrounded tank. This will determine the type of solid state circuit you can use.

For the solid state device, you have a choice of a bipolar transistor, FET, unijunction transistor, or tunnel diode. All give good performance with minor variations. For simplicity, only the first two are considered. However, if you have a favourite unijunction diode circuit you might try it. Your final decision will probably be based on what's on hand.

Fig. 2—Solid state g.d.o. with split-stator tank. A PNP transistor could also be used by reversing battery polarity.



NPN OR PNP CIRCUIT

An NPN transistor circuit I used in converting a Heath model GD-1B, which has a split-stator tank, is shown in Fig. 2. This circuit worked well with many transistors, including the 2N2926 and 2N708, up to 200 MHz.

A PNP transistor may be used in the same circuit if you reverse the battery polarity. In both cases oscillator output was more stable than in the original tube circuit. Less frequent adjustment of the sensitivity control was required during measurements.

COMMON-BASE CIRCUIT

If your tube g.d.o. has an ungrounded parallel tank, the common-base circuit shown on page 442 of the R.C.A. Transistor Manual, Series SC-12 (reproduced in Fig. 3) is suitable.

FET OSCILLATOR

The circuit I finally used to convert my Heath GD-1B is shown in Fig. 4.

CONSTRUCTION

After you have selected a suitable circuit, you are ready to start construction. Remove all the original oscillator and power supply components (if any) and their wiring. Don't remove the tuning capacitor, coil socket, meter or sensitivity control. Take care not to disturb the wiring between the tuning capacitor and coil socket.

The logical spot for the transistor is that vacated by the tube. You can mount a transistor socket on an adaptor plate placed over the tube socket hole. If you don't like transistor sockets, cut and drill a small piece of perforated board and mount it over the tube socket hole. Flea clips inserted in the board will allow permanent soldering of the transistor—but don't do this until all other components are mounted.

After assembling and wiring the components, temporarily attach the transistor leads to the flea clips with-

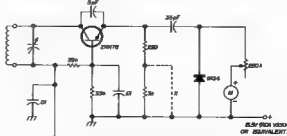


Fig. 3—Common-base g.d.o. circuit reproduced from R.C.A. Transistor Manual.

NOTE: X-AMPER USED FOR FREQUENCIES OVER 45MHz

* Reprinted from "Kam Radio," June 1978.

out soldering. This allows preliminary check-out.

Component leads must be kept short, particularly those connected directly to the transistor and the tuned circuit.

Small-value capacitors should be high grade silver mica. Bypass capacitors should be ceramic, not paper, to avoid stray resonances in the oscillator. All resistors are composition type, $\frac{1}{4}$ or $\frac{1}{2}$ watt.

The battery may be mounted in the space previously occupied by the power supply, using an appropriate bracket for the type of battery suited to your voltage and space requirements. Be sure to wire the battery connector with the correct polarity for NPN or PNP transistors.

In the circuits shown in Figs. 2 and 4 the sensitivity control is a 250K, linear-taper potentiometer. If your g.d.o. uses a lower value, I suggest replacing it with a 250K potentiometer and an s.p.s.t. switch to control the battery power.

CALIBRATION

Finally, check the dial calibration by beating the oscillator against a good communications receiver. Calibration may be a bit off if stray capacitances of the new circuit vary from the original. While most dippers are only approximately calibrated, you will want to maintain reasonably accurate calibration. Loosening the dial-locking screw and re-adjusting its position relative to the tuning capacitor will take care of most cases. However, if the calibration error exceeds this method of correction, or if the error occurs only on certain coils, the following tips will help.

Sliding a one-half inch strip of aluminum foil over two or three turns of the coil will lower its frequency. Conversely, a single shorted turn of wire placed around the form will increase the coil's frequency as you slide it toward the coil. Fig. 5 illustrates these methods. After calibration has

COUNTER USED FOR FREQUENCY MEASUREMENT

(Continued from Page 13)

Unit to allow counting for 1 second and 10 second intervals. The longer time interval is necessary to count the last column (cycles) when the frequency is 1 MHz. (as the input is divided by ten).

WHAT DOES IT DO?

Well, what does the thing do? It counts the 10 cycles per second output of my unijunction sweep generator. It counts the output from a small transistor oscillator using a 1 MHz. crystal. While counting for 1 second at this frequency the overflow indicator comes on but it is easy to see how many times the 10⁴ decade has counted. If you count for 1/10 second you lose a decade, of course, but the blinking display allows rapid calibration of an audio oscillator—you'll never go back to Lissajous figures. The last figure displayed will, of course, vary so that a frequency of 1 MHz. may be displayed as (1)000 (0)0 or (1) 00 001(0)—this is the nature of the beast.

COMMENTS

Some comments are necessary. The input as shown is not protected (I don't seem to use valves any more) and resetting 9×10^4 activates the overflow indicator. The amplifier in the Control Unit will act as a receiver if you put an aerial onto the input—put your finger on it and measure your frequency! It will also count 100/sec and if you feed it with insufficiently filtered d.c. It may be necessary, on occasion, to pay some attention to the input impedance of this amplifier.

It may be appropriate to point out that this was a project for the long winter evenings. Indoor summer temperatures in Sydney occasionally rise to a level at which transistor devices misbehave if there is no temperature compensation.

The three sub-units are mounted in a cabinet as illustrated in the photograph. The second 12 volt regulated supply is identical to the first and is included in the Control Unit.

Thanks are due to Mr. D. Cato for panel decoration of the Counter Unit and Dr. Bruce McMillan for the photographs.

REFERENCES

Sheldon, J. H., and Evans, J. 1965. Frequency and time standards; Application Note 58, Palo Alto, Calif.; Hewlett-Packard.

SUBSCRIPTIONS DUE

All members of the W.I.A. are reminded that annual subscriptions are now due and should be paid promptly to their Divisional Secretary. Non financial members will not receive a copy of "A.R." and back copies may not be available upon request. To preserve continuity of your files of "A.R.", please pay your annual subscription now.

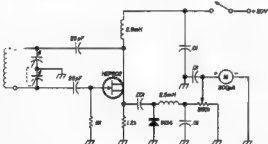


Fig. 4.—Grid-dip oscillator using an FET. This circuit provides greater sensitivity with less coupling because of FET's high input impedance.

CHECKOUT

After wiring and carefully checking the circuit, install the battery and transistor. Plug in a coil, apply power, and turn up the sensitivity control. If you don't get a meter reading, the circuit isn't oscillating or you forgot to use a heat sink when soldering the diode rectifier.

Assuming you obtain a reading, increase the control for full-scale meter indication and tune the capacitor from minimum to maximum to check for full-scale readings over the entire range. Repeat this for each coil. If any false dips are noted without the coil coupled to another circuit, you have a "built-in" resonance. Most likely this will occur on the higher frequency coils (40 to 200 MHz.) if lead lengths are too long or if non-resonant bypass capacitors were used.

been adjusted, the shorted turn or foil strip may be permanently cemented in place.

REFERENCE

1. L. G. McCoy, W1CPC, "A Field Effect Transistor Dipper," "QST," Feb. 1968.
2. Calvin Sondergoth, W8ZTK, "Transistor Oscillators," "73" March 1969.
3. J. R. Fleck, W1DXY, "Designing Transistor Oscillators," "73" August 1969.
4. "Transistor Oscillators," The Radio Amateur's Handbook, A.R.R.L. Staff, 1968, chapter 4, p. 47.
5. Rufus P. Turner, "How to Use Grid-Dip Oscillators," John F. Rider, Inc., New York, N.Y., 1960.

TECHNICAL ARTICLES

Readers are requested to submit articles for publication in "A.R." in particular constructional articles, photographs of stations and gear, together with articles suitable for beginners, are required.

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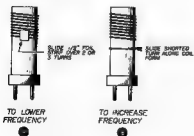


Fig. 5.—Methods for adjusting g.d.o. coils for calibration correction.

POWER IN A.C. CIRCUITS

LECTURE No. 8A

C. A. CULLINAN,* VK3AXU

Lectures 5, 6, 7 and 8 have dealt with some aspects of alternating current and this lecture proposes to carry these further and deal with the power in a.c. circuits.

In Lecture No. 8 we described briefly a perfect a.c. generator and stated that if a purely resistive load was connected to it, then all the power flowing in the resistor would be used. This is because the resistor has unity power factor and no power is returned from the resistor to the generator as all the power in the resistor is converted into heat.

In an alternating current circuit containing only pure resistance the current and voltage are in phase. That is, the voltage and current pass through corresponding parts of their cycle at the same instant.

For instance, if the generator voltage equation is

$$e = E_m \sin \omega t \\ = 311 \sin 377 t$$

then the current through the circuit is

$$i = I_m \sin (\omega t + \theta) \\ = I_m \sin (\omega t + 0^\circ) \\ = 5.66 \sin 377 t \text{ a.}$$

where m means maximum.

The voltage and current may differ widely in their amplitudes, the frequency factors are equal and the phase angle between current and voltage is 0° .

It should be obvious that Ohm's Law says nothing about maximum, average or effective values of current or voltage. Any of these values may be used, i.e. maximum current may be used to find maximum voltage, but maximum current is not used to find, say, the effective voltage unless the proper conversion constant is introduced into the equation.

It is the usual practice to consider all a.c. voltages and currents as "effective" values unless stated otherwise. The term r.m.s. is frequently used in place of "effective".

In a direct current circuit the power is equal to the product of the voltage and current, that is

$$\text{Power} = \text{Volts} \times \text{Ampere}$$

This is true, also, for alternating currents for instantaneous values of voltage and current, i.e. the instantaneous power is

$$p = e \cdot i$$



Guidance notes:

e is the voltage curve
 i is the current curve
 p is the power curve.

* 8 Adrian Street, Colco, Vic. 3204.

Continuing the series of lectures by C. A. Cullinan, VK3AXU, at Broadcast Station 3CS for students studying for a P.M.G. Radio Operator's Certificate.

When a sine wave of voltage is impressed across a resistance, the relationships of voltage (e), current (i) and power (p) are shown in Fig. 1. For clarity the amplitudes of the voltage and current are different.

The voltage which exists across the resistance is in phase with the current flowing in the resistance. An examination of Fig. 1 shows that at the start of the cycle, both voltage and current commence at 0° and each reaches its maximum at 90° . Both fall to zero at 180° , then rise to maximum in the opposite direction at 270° , then again fall to zero at 360° .

In this case there is no phase difference between the voltage and current and this is the condition for unity power factor, i.e. p.f. = 1.0.

The power delivered to the resistance at any instant is represented by the height of the power curve. This is the product of the instantaneous values of voltage and current at that instant.

The shaded areas under the power curve (p) represents the total power delivered to the circuit during one complete cycle of voltage.

It should be noted that the power curve is of sine wave form, having a frequency twice that of the voltage.

Also, it should be noticed that the power curve (p) lies entirely above the X axis, as there are no negative values of power in the proposition under discussion although both the voltage and current are below the X axis for one-half of the cycle.

This may be explained in a simple manner. In Lecture No. 8 reference was made to toaster elements having very little reactance. Now if we connect a toaster, with this type of element, to the a.c. mains it transforms electrical energy into heat. On the positive half-cycle of the a.c. mains (above the X axis) the element gets hot. Now on the other half-cycle (below the X axis) it remains hot; it does not get cold during this half-cycle. For simplicity, we have treated the toaster element as a non-reactive resistor because the reactance is so low. The purist may shudder because there is a little reactance. The artificial aerial described in Lecture No. 6 has a measured resistance of 51 ohms and an inductive reactance of 20 ohms at 1 MHz, so its reactance at 50 Hz. is mighty small.

One other thing will be noticed from Fig. 1, and that is that when the voltage and current both have the same sign (either positive or negative), then the power is positive (above the X axis).

The maximum height of the power curve is the product of the maximum values of voltage and current, thus

$$P_{\text{MAX}} = E_{\text{MAX}} \times I_{\text{MAX}}$$

The average power delivered to a purely resistive load is shown by the line a-b in Fig. 1, which is half the maximum height of the power curve. From this we have

$$\text{Average Power} = P = \frac{P_{\text{MAX}}}{2}$$

$$\text{and } \frac{P_{\text{MAX}}}{2} = \frac{E_{\text{MAX}} \times I_{\text{MAX}}}{2}$$

$$\therefore P = \frac{E_{\text{MAX}}}{\sqrt{2}} \times \frac{I_{\text{MAX}}}{\sqrt{2}}$$

$$\therefore P = E \times I$$

Therefore the a.c. power consumed by a resistance load is equal to the product of the effective values of voltage and current, i.e. r.m.s. values.

As in direct current circuits, this power is measured in watts.

REACTIVE LOADS ONLY

Having dealt with power in an a.c. circuit containing only pure resistance, we now turn our attention to an a.c. circuit containing only pure reactance as this will be a logical step towards an a.c. circuit containing both resistance and reactance.

Fig. 2 shows the voltage (e), current (i) and power (p) relationships when a sine wave of voltage is impressed across an inductance which has no resistance. This delightful state of affairs cannot exist in practice, but it is desirable to assume a pure inductance for this part of the lecture.

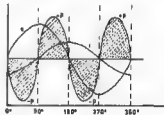


FIG. 2

Guidance notes:
 e is voltage.
 i is current.
 p is power curve.
Power above the axis is plus and below is minus.
The shaded portion is power within the power curve.

It will be seen that the voltage has been drawn so as to start to rise in the positive direction, above the X axis, at 0° and that the current starts to rise positive 90° after the voltage started to rise. This means that the current is lagging behind the voltage by 90° , thus there is a phase displacement between the voltage and the current. Compare this with Fig. 1 where there was no displacement.

Now let us examine Fig. 2 in detail. When current is increasing from zero to maximum positive, during the interval 90° to 180° , power is being taken from the source of electro-motive force (e.m.f.) and is being stored in the magnetic field around the inductance.

As the current through the inductance falls from its maximum positive value at 180° to zero at 270° , the magnetic field is collapsing, thus returning power to the source. This is shown by the shaded portion of the power curve p , below the X axis.

During the excursion of the current from 270° to 360° , although the current is now negative (below the X axis), the power curve is positive (above the X axis).

From 360° to 90° of the next cycle the current drops to zero at 90° , the magnetic field around the coil has been collapsing and power being negative is returned to the source.

Thus we have the situation that positive power is followed by negative power.

The positive power is taken from the power source and the negative power is returned to the source, therefore the circuit does not consume power although power alternately flows from and to the source.

When a source of alternating current is impressed across a pure capacitance power is taken from the source and stored in the capacitance whilst the voltage is rising from zero to maximum in the positive direction, 90° to 180° . As the voltage falls from maximum at 180° to zero at 270° , the capacitance discharges back into the source, but this is negative power. The voltage then becomes negative from 270° to 360° lying below the X axis but the power is again positive, being taken from the source.

At the beginning of the next cycle the voltage starts to fall from 0° to 90° and the power is returned to the source as it is negative power.

The capacitive circuit may be understood by referring to Fig. 2 and transposing e and i . In this case the current leads the voltage by 90° .

An examination of Figs. 1 and 2 show that when the voltage and current are both of the same sign the power is always positive irrespective of whether or not they are positive or negative (above or below the X axis). However, when they are unlike, then the power is negative.

Further examination of Figs. 1 and 2 shows that when the circuit is purely resistive, there is no negative power because the voltage and current, being in phase, have the same sign at all times.

However, when the circuit is purely reactive there is a phase displacement between the voltage and current, at times they are of the same sign and at other times they are of opposite signs, thus there is positive and negative power in the circuit.

In a purely reactive circuit no power is absorbed by the reactance, however power does flow to and from the source.

This is known as *reactive* or *apparent* or *wattless* power as it can be determined by voltmeter and ammeter

readings and is given by $P = E \times I$ and is measured in **volt-amperes (VA)** or if large in **kilovolt-amperes (KVA)**.

RESISTANCE AND INDUCTANCE IN SERIES

So far we have seen that when the load is purely resistive the voltage applied across the resistance and the current flowing through the resistance are in phase, whilst in a circuit where the load is purely reactive the voltage and current are 90° out of phase. The voltage will *lead* or the current *lag* the other when the circuit is inductive and the voltage will *lag* and the current *lead* the other when the circuit contains capacitance only.

However, circuits usually contain both resistance and reactance.

In Fig. 3 is shown a circuit containing resistance and inductance. $R = 6$ ohms and $X_L = 8$ ohms. These values have been chosen for ease in computations.



Using the methods shown in Lecture No. 6, the following results will be obtained:

Current through circuit = 10 amp.
Voltage across resistance = 60v.
Voltage across inductance = 80v.
Phase angle θ between voltage and current = 53.1°

thus the voltage *leads* the current by 53.1° , or the current *lags* behind the voltage by 53.1° .

RESISTANCE AND CAPACITANCE IN SERIES

If a capacitance of 8 farads is substituted for the inductance of Fig. 3, calculations will show that the same answers will be obtained, however in this case the voltage will *lag* the current or the current *leads* the voltage by 53.1° .

RESISTANCE, INDUCTANCE AND CAPACITANCE IN SERIES

We have shown that inductive reactance causes the current to *lag* behind the voltage and that capacitive reactance causes the current to *lead* the voltage, hence these two reactions are opposite in effect. If the inductive reactance and the capacitive reactance have exactly the same value, then they cancel each other exactly, i.e. taking the two variations for Fig. 3, we have $X_L = 8$ ohms, $X_C = 8$ ohms, and if both are connected in series we have:

$$+j8 - j8 = 0$$

so the net reactance is zero. This is the condition for series resonance.

At one time in Australia's history there were wide differences in the voltages and frequencies of a.c. power supplied to the public, but nation-wide voltages between 200 and 250 volts at a frequency of 50 cycles per second is becoming standard. Western Australia used 40 c.p.s. for many years.

For Fig. 4 a voltage of 220 has been selected. This figure shows a series circuit containing resistance, inductance and capacitance having different values to those given in the circuit problem of Lecture No. 6 so that the student may gain experience in working out this problem and checking the answers given here.



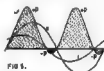
$R = 100$ ohms
 $X_L = 132$ ohms
 $X_C = 204$ ohms

Impressed voltage = 200 volts
∴ voltage across resistor = 179 volts
voltage across inductance = 236v.
voltage across capacitance = 365v.
current flowing in circuit = 1.79a.

Power factor is 0.8 (to nearest decimal place; 0.812 to three places). The impedance is 123 ohms, and the phase angle is -35.8° , which means that the voltage lags the current by this phase displacement.

The net reactance of the circuit is:
 $+j132$ ohms $-j204$ ohms =
 $-j72$ ohms.

This shows that the net reactance is capacitive and the circuit resolves itself into a resistance of 100 ohms and capacitive reactance of 72 ohms in series.



Guidance notes:
Drawn as closely as possible for voltage, current and power for circuit of Fig. 4.
 e is voltage a.c.v.e.
 i is current a.c.v.e.
 p is positive power.
 p is negative power.
In this case most of the power is taken by the circuit and only a small amount is shown as the minus p is returned to the source.

Fig. 5 represents the relationship between voltage, current and power for the circuit and values of Fig. 4, and an attempt has been made to draw Fig. 5 to scale.

e is the impressed voltage
 i is current flowing in circuit
 p is the positive power in circuit
 $-p$ is the negative power in circuit
 θ is the phase angle.

As has been stated previously, the instantaneous power in the circuit is equal to the product of the impressed voltage and the current through the circuit.

It has been stated, also, that when the voltage and current have the same sign, irrespective of whether they are both positive (above) or negative (below the X axis) they act together and take power from the source. However, when their signs are different, again

irrespective of their positions in relation to the X axis, they are operating in opposite directions, the power is negative and is returned to the source.

The apparent power, $P_a = EI$, whilst the true power, $P = IR$ or $P = E_a I$

where E_a is the voltage across the resistance in the circuit.

Apparent power is sometimes called total power, whilst true power is the power which produces work.

The power factor is the ratio of the true power to the apparent power.

$$\text{Power Factor (p.f.)} = \frac{P_{\text{true}}}{P_{\text{apparent}}} = \frac{P}{P_a}$$

$$\therefore \text{p.f.} = \frac{IR}{EI} = \frac{R}{E}$$

$$\begin{aligned} \text{then because } E &= IR \\ \text{p.f.} &= \frac{IR}{IR + IX} \\ &= \frac{R}{R + X} \end{aligned}$$

Thus the power factor of a series circuit may be obtained by dividing the resistance of the circuit by its impedance.

The power factor may be expressed in terms of the angle of lead or lag.

$$R + jX = Z \cos \theta$$

$$\therefore \text{power factor} = \cos \theta$$

$$\text{and true power, } P = P_a \cos \theta$$

$$\text{or true power, } P = EI \cos \theta$$

From the data given earlier,

$$P = IR = 1.79 \times 100$$

$$= 320 \text{ watts (nearest whole number)}$$

$$\text{or } P = E_a I = 179 \times 1.79$$

$$= 320 \text{ watts}$$

$$\text{or } P = EI \cos \theta =$$

$$220 \times 1.79 \times \cos 35.8^\circ = 320 \text{ watts.}$$

Power factor is usually expressed as a decimal and

$$\cos 35.8^\circ = \cos 35.8^\circ = 0.812.$$

If expressed as a percentage

$$\text{p.f.} = 100 \cos 35.8^\circ = 81.2\%.$$

RATING OF A.C. GENERATORS

Manufacturers of alternating current generators rate their machines as being capable of delivering a certain number of kilovolt-amperes (KVA) and not as being capable of delivering so many kilowatts (KW).

This means that they guarantee that the generator if kept revolving at the correct speed will generate a certain voltage and that it will stand a certain current without overheating.

This is because they cannot guarantee it as being able to generate a specified or certain amount of power under all conditions of use because they do not know the nature of the load that the user will use.

Suppose an a.c. generator was guaranteed to deliver 10 KW at 200 volts and that it was connected by the user to a load having a power factor of 0.7.

$$\begin{aligned} \text{Then it would have to supply an} \\ \text{apparent power of } 10,000 \div 0.7 = \\ 14,285.7 \text{ watts} \end{aligned}$$

or 14,286 watts to nearest whole figure. So that the true power should be equal to the apparent power,

$$14,286 \times \cos \theta (0.7).$$

This means that the generator would have to supply a current of $14,286 \div 200 = 71$ amps. (to nearest whole number) instead of $10,000 \div 200 = 50$ amps.

The additional current that the machine has to produce would cause additional heating and could damage the machine.

From this it can be seen that the rating of a.c. generators is dependent on the amount of heat that the windings can stand.

Thus a.c. generators are rated in kilovolt-amperes which is a direct measure of the heating factors in the windings and a true measure of the capacity of the machine to do work.

Large transformers are rated in the same manner and for the same reasons. Sometimes small transformers are rated in volt-amperes (VA). Some of the transformers detailed in Radio Parts Pty. Ltd. catalogue have their power ratings shown in VA because the manufacturers do not know the types of loads that users will employ, as it is one thing for a manufacturer to specify that a transformer is to be used for a particular purpose, then to ensure that the purchaser will use it for that purpose.

RECAPITULATION

In this lecture we have assumed that the resistances were pure resistances, that is non-reactive. It is fairly easy to make resistances having little if any inductance, and with very little distributed capacitance. However, it is virtually impossible to make an inductance which does not have some resistance and capacitance, also it is impossible to make a capacitor which does not have some resistance, although it may be very small, also the capacitor

may have a small amount of inductance, but it was desirable to make the assumptions that were made.

In an a.c. circuit containing only reactance the power factor is unity and in a circuit containing only reactance the power factor is zero.

In a well designed reactance the power factor will approach zero and the current will either lead or lag the voltage by nearly 90° . If the reactance is not well designed, then the power factor will lie between zero and 1.0 and the angle of lead or lag may be far less than 90° and losses in the reactance will be large.

Finally, in Lecture No. 5 there was shown the effective value of an alternating current. The effective value of an alternating current is the equivalent value of a d.c. current which would give the same power dissipation in a resistance R as an alternating current amplitude I effective.

The power dissipation in the d.c. case is:

$$P = I^2 R,$$

$$P = VI, \text{ or } V^2 \div R$$

where P is the power, I is the d.c. current, and V is the d.c. voltage.

The power dissipation in an a.c. case of pure resistance is:

$$P = I^2 R,$$

$$P = VI, \text{ or } V^2 \div R$$

where P is the power, I is the effective a.c. current, and V is the effective a.c. voltage. The term root-mean-square (r.m.s.) means the same as effective. The term r.m.s. is derived from the fact that it is the square root of the average (or mean) value of the squares of all the different values the current can take during one complete cycle.

r.m.s. effective and virtual all mean the same thing when dealing with a.c. circuits.

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Overseas Magazine Review

Compiled by Syd Clark, VK3ABC
and R L Gunther, VK7RG

THE AUSTRALIAN E.E.R.

October 1978 CD Ignition System, VK12VG. A work mate says his "Jag" goes better with me. My Holden is fast enough without Your choice, friend.

Feedback is Complimentary Symmetry Amplifiers, VK7DZ. Self explanation.

Third Party Traffic, VK7RG. Seems to me now, and has for years, that the government operated commercial communications system would not be damaged by granting amateurs the right to communicate for others. Much good could come from such a right because more amateurs would become trained communicators.

Review copy by courtesy of E.E.R., P.O. Box 177, Sandy Bay, Tas., 7008. One year £10.00, three years £24.00, to R. A. Walton, 118 Wilmore, Tas., 7108.

"HAM RADIO MAGAZINE"

September 1978—

Editorial: Jim Flak continues his series of non-political interesting discussions of new technical developments. This time on microwave acoustics, but "micro" sound waves on piezoelectric resonators. The result is an improved filter, delay line, resonator, or amplifier in the region below 30 MHz.

An Integrated Circuit Balanced Modulator.—The Motorola MC1596Q can be used as balanced modulator, a.m. modulator, frequency product detector, mixer, or frequency doubler. Consists of a dual differential amplifier driven by a standard differential amplifier. A couple of resistors and a chip provides constant current drive. (Availability in Australia is probably questionable, at least in 1971, but the article would be worth a look in computer translators, using the diagram furnished in this article, it could be well worth doing. There are one more interesting balanced modulator shown, he claims a dynamic range of 90 dB, the actual figure is more like 30 dB.)

The Mainline ST-5 E.T.T.Y. Demodulator.—Uses two linear ICs to reduce complexity and cost by an order of magnitude, compared to previous designs.

An A.M. Receiver for Two Metres.—The author discovered that by doing a good job at the workbench it was actually possible to get better results than from a commercial unit. The circuit is simple, and double conversion, with ICs as i.f. discriminator and a.m. power. A 10.7 MHz bandpass i.f. and 455 KHz detector give adequate gain.

A Multimetre Transmitter for Six and Two Metres.—Addition of 825B valve linear amplifier and automatic a.m. modulator, higher power output on m or a.s.b. 2 or 6 metres.

A.F. Impedance Bridge.—Unlike the Antenna Noise Bridge which has its own signal source this is test it by bridge which takes its signal from the transmitter. Inductive component is analysed by looking at capacitive component and transferring by bridge to the Smith Chart, which is described briefly; for more comprehensive treatment of the Smith Chart see the November 1978 issue.

Neutralising Small Signal Amplifiers.—Valves and FETs which need neutralisation as converters or pre-amplifiers can display annoying instabilities. This author shows how to overcome them, thus giving the higher gain and lower noise provided by optimum neutralisation.

Electronic Counter Dials.—A readout of frequency for the v.f.o. of his receiver. Instead of the now more conventional cryo-counting method, he employs a trick which takes the frequency ranges the v.f.o. is heterodyned with a crystal standard and the best noise is a divider circuit which reads out on simple gas-filled glow lamps.

Self State Audio Oscillator-Modulator.—Answer sine wave phase shift transistorised a.f. oscillator that works at 4.5v, and uses no lumped inductance.

Resonance Network.—Very useful, but only if you test it out and pass the test so that it is readily available when needed.

Parasitic Oscillations in High Power Transmitter A.F. Amplifiers.—Transmitters present unique problems not enjoyed by valves in class C amplifier service and some of these

are explored here. Must-reading for all semi-conductors-at-any-price enthusiasts.

Direct Conversion C.W. Transceiver Operation.—C.W. operation of transceivers is much facilitated by sidesteping the need for beaters at the stations involved. Rather than being the disadvantage popularly believed, it facilitates C.W. operation and improves c.w. sensitivity. It is best achieved by standardisation of peaked resonant filters in all relevant c.w. transceivers. The Kapsal Bench.—Finding faults in r.f. and i.f. amplifiers, semiconductors, and valves. Very useful, but of considerable importance in between the stations involved. The author's caution: "A trouble in the fence may be caused somewhere else". The a.c. system is a favourite culprit, including the 5 meter circuit.

October 1978—

The S.W.R. Meter.—You can trust the reading of this a.w.r. meter, which you cannot do with "a.w.r. bridges, antennascopes, or other gadgets that base their calibration accuracy on the characteristics of their semiconductor diodes." The technique described is borrowed from standard microwave procedures.

The Sideband (or C.W.) Mixer.—A pocket sized direct conversion receiver for 80 and 40 metres, using FET product detector in the common base mode. Audio is fed through a few-stage IF amplifier, and then into a commercial a.f. power module.

Voltage-Peak Receiving Antenna.—A new two-inch-high shield antenna which forms a 3 ft. whip below 40 MHz.—And furthermore, its gain is flat from 30 KHz. to over 50 MHz.

Designing with IC Voltage Regulators.—Inherent device constraints are analysed and design examples are given to obtain optimum regulator performance.

Linear-Pass Network.—An aid for determining signal attenuation due to variance in earth-ground distance.

Converted BC109 for 3 MHz.—Conversion to FETs and thus retaining the advantage of i.f. operation and the other obvious benefits as well. MOSFETs are used, and are used.

To obtain operation at h.f., semicon broadband converters are added.

Low Cost Converter for 433 MHz.—A circuit using inexpensive FETs that gives a good account of itself. Easier and better than valves in this instance.

Frequency Tuning with S.S.B. Equipment.—Hints on pinpointing operating frequency in the a.s.b., c.w. and r.t.y. modes.

Identifying Antennas with a V.A.—A well designed workbench is essential for experimenters.

Interference to Thyristors.—How to use these silicon controlled rectifiers and traces. Very good, and detailed.

Modular Two Metre Converter.—A modular approach to a h.f. front end design, with special emphasis on constructional details. Use of glass-epoxy board with large areas of copper to reduce inductance and capacitance.

Improving the Voice Commander F.M. Set.—Rather obscure, from an Australian point of view.

"OEM"—The Oriental Ham Magazine

September 1978—

The Interiors, KIKKA.—Discusses signals close to 14280 and 7130 and others which the author states should not be where they are.

Year S.W.R. Meter and Yes, VSWR.—How to get the most out of a device which can give misleading results or at least results which are capable of misinterpretation.

Codes Explained, VSWR.—The author explains the various codes which are commonly used on radio circuits.

Bridge Rectifiers, And Patrick.—Modern circuits for modern solid state units.

November 1978—

Using Old Motors, ZS1NU.—Sets out to tell you how an old washing machine motor can be used to rotate a beam. Have you ever thought of using a motor belt or rope between the rollers of an old washing machine wringer?

A.M.-S.B. Reception, ZS1NU.—Circuit of a 12AU7 valve as a product detector in the older type receiver.

Modification to KW Victory Mk. I S.B. Transceiver, ZS1NU.—Changing the 7 MHz. band from u.s.b. to l.s.b.

How To Use R.F. Power Transmitters, by WATKKE.—Reprinted from "Amateur Radio," May 1978.

"SPECTRUM"

September 1978—

This little magazine is a quasi-duplicated effort by V.I. Schickling. It is about half of its more than 30 pages per month is

taken up with interesting Radio Amateur activities and v.h.f. all over New Zealand, and the rest with technical articles in the best experimental tradition. As with all magazines, some issues are better than others, but the overall standard is high, and the magazine is well worth the modest subscription price, \$150. The address is Spectrum, P.O. Box 5584, Auckland, New Zealand.

Contact Potentials.—Listing standard potentials of various metals, relative to calomel.

Ferrite Tube Chokes.—Listing of impedances at various frequencies of 1 inch length of ferrite tube with one or two turns of wire through it.

Corrosive Comments.—More on relative corrosion abilities of various metals in contact with each other, in cathodic metals (e.g. brass, copper, nickel) are placed in contact with anodic metals (e.g. magnesium, zinc, iron, steel). The cathodic one will corrode the anodic one.

Tail 80.—A complete transmitter-receiver, valued, £150/0/75 in final.

A 3 Metre QRP/40A Linear Amplifier.—Complete details. Copper-tubing tank, 87500 h.t. transistor for screen stabilisation.

Floke FETs.—Methods for avoiding static (and other) overload catastrophes when using MOSFETs. Best of all, he suggests using product detectors, and then into a commercial a.f. power module.

Wide Audio System for a Receiver or QRP Modulator.—Part 3 in a series of IC projects. The use of the TAA300.

V.H.F. Aerials for the Amateur.—Polar plots for the construction of the five aerials tested and described in the August 1978 issue of "Spectrum".

The Log-Periodic Yagi.—Full constructional details. Very nice.

A Beginner's Project.—Part 1. Two JFETs in a cascade r.f. stage.

October 1978—

(Noted in an adv.—There seems to be nothing wrong with the supply situation in N.Z. 1200 MHz, 353CST transistors for 50c each, 80c for 100c.)

A Band-Checker.—A combination full strength meter, marker oscillator and crystal activity checker.

A Band-Checker.—Design for a metal bander.

Modifications to Tail 80 for use on 146 MHz. Also modifications to Tail 80 and Tail 80F.

SWR 1:1 Fact or Fiction?—A good article, full of commonsense.

Series State FET Converter.—A number of magazine have unwittingly propagated the error set by Sept. 1967 "QST": The gate of the second FET should not be grounded directly. A "series" circuit is preferable to "series cascade" to allow the highest gain and lowest cross modulation achievable from just 12-BV or 15-BV.

A Protected 15V. Power Supply (Part 4 in a series of IC projects).

The Oscillator.—Describing the availability of a commercial unit to time the length of "overs".

C. Language.—How to abbreviate and retain intelligibility—14 says here. A complete vocabulary decoder is furnished.

More C.W. Sending Aids.—More of same, more sophisticated version.

"V.E.F. Communications"

November 1978—

A S.B. Transceiver with Silencium Transistor Complement, Part 4.—Power supply and i.f. amplifier by DLHRA.

Crystal Amplifier for the Two Crystal Oscillators of the 145 MHz. MOSFET Converter used in the DLHRA a.s.b. transceiver, by DLHRA.

Synthesis V.F.O. for 24 MHz, DLJWR.

Simple Shunted Audio Filter, DLJWR. The output begins to fall at 2 KHz. and then falls at the rate of about 25 dB/octave. Different circuits and characteristics are shown.

Speech Processing, DLJWR.—Various types are discussed.

Stripline Transceiver for 70 Cm. DCHY.—Solid state except for an EC805 valve.

A Simple V.H.F.-U.V.F. Calibration Spectrum Generator, DLHRA. The circuit is suitable up to about 500 MHz. 5 dB above noise in a receiver with a noise figure of 7 dB. With a crystal signals are approximately 30 dB stronger.

Neutralisation of the DLXW/DJ450 Calibration Spectrum Generator, DLJWR.

Two Circuits for Automatic Band Scanning, DLHRA. The lazy man's way of watching the band.

REPEATS

The installation of repeater stations for the Amateur Service is now quite widespread throughout Australia. Probably the latest example is that of VK2ZP very close to the attractive solid state device running 15 watts output on Channel 4. A full description of its working capabilities and possibilities was outlined in the January meeting of the W.I.A. at the home of Mr. and Mrs. Ian Crampton, VK2ZP and the completed equipment was on display. Much good thought and excellent engineering practice went into its design and construction and it is fine to find that even those concerned, Rex VK3PQW was observed on Sunday, 31st Jan, giving the repeater a good workout from his home at Crafers Creek. The good work was done on the 10th and 11th of February.

The following repeaters are either operational or in a testing condition. Ch. 1, Gold Coast, N.S.W.; Ch. 1 in, Ch. 4 out, Central N.S.W. (may soon operate on Ch. 1 out); and the following on Ch. 4 Bendigo, Geelong, Latrobe Valley, Mildura, North Tasmania and Adelaide. A channel has been allocated to the Albury area—possibly Ch. 1. Thanks to the Geelong Amateur Radio and Fv Group Newsletter for this information.

Keywords: child sexual abuse; disclosure; social support

to think it would be fair to say any most operators have had quite a good DX season this year. The reason for this is the greater consistency of good openings to most all areas on 8 metres, some very good high openings on 10 and 12 metres. This was noted. Signals from ZL have shown an increase over last year and with the appearance of the new 2000 watt station, the new 1000 watt equator working stations in VK3 and VK4, considerable more interest than usual was shown in the 8 metre band. The new station of the "Station with the big sound" Bob VK3EDK, on one occasion, but Bob was too busy to work the 8 metre band. The new stations on the equator? Ken VK3ZJJ received some distinction by working ZL again. This time he worked ZL 88, thus giving his "Worked all ZL Call Areas" for a metre. Ken's lengthy record for which I thank you, comments on the number of short skip openings from VK3 to VK3 and VK1, and the number of openings from VK3 to VK1 in January with all signals many dBs over 88. Bob remarked also on the large number of openings from VK3 to VK1 in January. In South Australia was received at good strength. He also worked VK3ZAG at Carnarvon in Western Australia. Very best wishes to all.

Further noise from Bob's pen shows that he was successful in working Lance VK4KAZ with signals up to 88 on 2 metres on 12/1/78. The opening lasted only from 1330 to 1335. Lance was a good signal on 6 metres but not over strong, at the same time, VK4KAZ at that time were hearing both VK4K and VK4Ks, indicating an extensive patch of strong Ks. Lance also heard VK4KAZ after the opening with Bob's conclusion, but the band closed before contact could be made. Alan VK4KEZ, at Deniliquin, was also heard on 2 metres the same day.

It looks as though the efforts of Eddie VK1VF were not in vain when he went portable on 44L. Ginger and worked Ron VK3AKC in Geelong on 2 metres, and Ian VK4ZDW (Mt. Buller) on 433 MHz., a distance of about 180 miles. Ian also worked VK1CG on the same occasion on 433.

Bob VK1AQT concludes his letter by asking the question whether anyone in VK8, particularly in the Alice Springs area, where there now quite a group of Amateurs, are interested in building 2 meter equipment with a view to making contact with the "western or eastern States"? It's a little over 500 miles from Adelaide, and probably nearer 1200 to Melbourne, but no doubt it could be done some time if there are any interested parties. Bob has recently joined that rather select few who now only require a VK8 for W.A.S. on the 2 meter band, and is now looking for a QTH, I hope to take a 2 meter gear to Alice Springs during the winter months--will this help?--VK8LP.)

Another correspondent to write to me this month has been John VK3BHO, at Warilla, 100 miles south of Sydney. John is somewhat restricted in his 6 metre operating as he is a part time amateur, but he has a very well controlled, with the receiver tunable over a limited range of 31.5 to 32.4 MHz with a ground plane antenna up 30 feet. However, he has a good selection of ELA, ZL and ZLZ antennas, plenty of ELA, and worked ZL1RS and ZL2AAH, apart from getting amongst the Australian DX. Here is an example where a person with limited equipment has set about making the most of it, and has a wide range of his contacts. However, limited trans-

mitter power makes itself known when so many stations can be heard but not worked. Good luck John

MOONBOUNCE NEWS FROM VIKAT
AND ELSEWHERE

Ray VK3ATN hopes to work QILTF on moonbounce during February, and to this end he has work under way for a new antenna system. He is running 100 watts c.w. on 1296 MHz, using a pair of 3CX180-As water cooled—it is possible to get 400 watts output from these tubes. Here are a few details of Ray's dish antenna.

Foundations are 18 feet deep and consist of four holes drilled out to 10-ft. diameter. The tower is 24 feet high. The existing 30-ft. dish gives marginal results, so a 35-38 ft. dish is being installed. Having twice the surface area, an improvement of 3 dB. gain on receive and transmit is expected. (For Sale: One 30-ft. dish—contact Ray VK3ATN).

Under construction sixty feet south of the main dish is a 25-ft. tower having two-ft. square foundations ten feet deep. A tractor rear axle is used for a polar mount, and a motor drives in opposition to the earth's rotation with a 2,075,000 to 1 reduction from 1400 r.p.m.

The 2 metre array consists of Swan-type yagis, each having 14 db. gain over a dipole, and cross polarised. The total antenna has 32 x 16 ft. long crossed yagis twelve feet apart. The feed impedance is 300 ohms in the middle and the gain in excess of 30 db.

These facilities are available to any group provided that they bring their own equipment and help Ray with some of the work. Facilities are available for 144, 433 and 1296 MHz. moonbounce. Ray may try meteor-scatter to VES shortly.

For moonbounce work, the following sked times have been arranged:

Saturdays and Sundays—WTRP, 14300 at 0000 GMT.

Sundays—GLTF, 14130 at 0000 GMT.

Any day (tentative)—K6MYC, 14290 at 0000 GMT; KP4DJN, on 23115; and K6LJN (no details).

KFSDJN has a 100-ft. dish steered by movements of the feed-line, and may soon be constructing a 300-ft. dish. ZLIMO has worked 5M2BAE twice on c.w. on 2 metres on Nov 28-30. ZLIAER is out of the moonbounce business for awhile due to work commitments on space tracking near Auckland. (Reprinted from W.A. V.H.F. Group News Bulletin, Dec. 1973.)

In a future issue I hope to have a paragraph with some information about a "dyed-in-the-wool" C.W. operator of many years standing who finally saw the light of day and tried V.H.F., and phone at that too! Results: very good. There's a moral to the story, but let's wait for the paragraph.

That's all for this month. Still trying to get someone into "Meet the Other Man" from time to time. All you need to get into the print will bear with me a little longer, it takes time to get right around. If any of you think you have a rather outstanding record in the field, please write me and let me know. I should not write to me and ask for the detailed form sent to all those involved, it's okay when returned, then it is just a matter of waiting for the results. I don't want to appear in these notes. By now, everyone should have a fair idea of what is needed anyway. I'll be glad to write a rough for the month. "The only suitable gift for the man who has everything is your deepest sympathy and love." did you know a Volkswagen has been referred to as "The only suitable gift for the man who has everything." The Voice in the Middle.

MEET THE OTHER MAN

Mike George Francis, VK5BAV/T, is VK5CEG/T of Morwell, 30 miles east of Melbourne, whose interest in radio started while at Wonthaggi Technical School and becoming a radio amateur. He was a radio technician and an electrician but became interested in small ship radio servicing. Thus gaining valuable m.f./h.f. experience under a special experimental license. In 1950 he turned his interests to v.h.f., building up a v.h.f. base-mobil network on 143.30 MHz. (V3E3K) which he put in service when he moved to Melbourne at last. Newborough, where his interests blossomed into VK5BAV. Radio in 1958, with the call sign of VK5CEG, a well known call sign for the next 14 years. His first v.h.f. operation was 144 MHz. a.m. on 144.15 MHz. He also worked 144.15 MHz. in March 1968. His first 8 metre QSO was in July 1967 on the new 56 MHz. band, and later on the 50 MHz. band when it changed in 1968. He has since worked 144.15 MHz. and experienced his first 50 MHz. ex DX, following

Continued on Page 11)

AMATEUR BAND BEACONS

VK0	53.344	VK0GR	Antarctica.
VK3	144.700	VK3VE	Kilsyth, 20m. E. of Melbourne.
VK4	144.390	VK4VV	107m. W. of Brisbane.

VK3	\$3.00	VK3VF	Mt. Lofty
	144.800	VK3VF	Mt. Lofty
VK8	\$3.00	VK6VF	Tuart Hill
	52.800	VK6TS	Carnarvon
	144.500	VK6VE	Mt. Barker
	148.000	VK6VF	Tuart Hill
	435.000	VK6VF	ion by arrangement)
VK7	144.200	VK7VF	Christchurch
VK7	144.800	VK7XI	Christchurch Island
ZL3	148.000	ZL3VHF	Christchurch
JA	51.985	JAIJG	Japan
W	50.091	WNSKW	U.S.A.
HL	50.190	HL5W1	South Korea

A further addition to the beacon list can be made again this month with Roger VK8CR stationed at Casey base, operating a continuous beacon on 53.544 MHz, sending the call sign at 2 words per minute for 55 seconds, followed by a 3-second break. Beam heading from Melbourne about 86 degrees West. (About S.W. for VK8.) As well as watching 2 metres, Roger operates between 14130 and 14390 KHz. A.S.

Most evenings
While dealing with the frozen school, mentioned
about a half hour of two other v.h.f. experiments
going down that way. Phil ex-VK3FT, now
VK3FT, expects to be operational on 6 and
10 MHz s.b.b. in a few days. He will be
establish some v.h.f. contacts with Australia
via auralnet sometime. Please send me some
names Phil will be going to see down
here. I will be on 10 MHz ex-VK32KZ.
VK0MX, who will be briefly operational on
14 MHz s.b.b. later followed by EL333 Mifflin
will be on 10 MHz. I will be on 10 MHz
operation at Mawson is VK0ZPO--Ed.]
collectively, with a bit of luck, VK3 may
be on 10 MHz. I will be on 10 MHz. I will be
particularly next DX season if the boys down
there can keep going that long. Their ex-
periments are making me impatient.
so I will try and get some news from them

Getting back to beacons for a moment, we always depend on my best to ensure the list of frequencies is as accurate as possible. If the locations have been altered, a variation in frequency has been made, please let me. There is nothing worse than something being changed frequency or for some other reason not to be listed. For newcomers to the service, the listing of frequencies can be useful indicators of band openings. They have an advantage in that they are the most reliable, as they are monitored for long periods, can be done by the average receiver and knowing that the frequencies are being built up is sufficient that they will be heard before a large area of band space they cover. The following will probably be found to be useful.

Channel 9—51 740 MHz	Western N.S.W.
51 750 MHz	Brisbane
51 780 MHz	Melbourne

Further afield but often heard is WNTV at 50.10 MHz from Wellington, New Zealand. Of limited interest will be Channel 5A from Wollongong, N.W., on 143.70 MHz. Other stations are heard from the coast of New Zealand during the height of DX seasons as those operating on Channel 3 about 82 MHz. These can be pointers towards suitable conditions for DXing from New Zealand. Stations in the southern States the chief stations to watch are Ch. 3 are located mainly in Queensland, in the Darling Downs area, Rockhampton and the coastal stations. The latter are heard at locations many times this year, with excellent signals, sometimes all three at once, at others one fading out to allow the other in, etc. The stations are heard mostly from the test patterns in the mornings.

Just a fill word while on t.v. stations. It is noted with interest in the January 1977 "E.A." listing of Australian television stations that the use of Channel 8 Translator Stations is becoming quite wide spread, particularly in N.S.W., so I guess there will be a few grumbles from those areas before long! Just take a peep at pages 104 and 105 to see how wide-spread television has extended now!

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Amateur Radio, March, 1971

COOK BI-CENTENARY AWARD

The following additional stations have qualified for the Award:

Cert. No.	Call	Cert. No.	Call	Cert. No.	Call
973	DK3PO	1031	AX8KR	1090	ZM1PV
974	WB8DKC	1032	K4RHQ	1091	WS2WX
975	AX8HDT	1033	KH8GQ	1092	KG8HW
976	AX8CC	1034	AX8AC	1093	AX8JL
977	AX8UT	1035	ZM2VH	1094	AX8QL
978	JA1VR	1036	W1KXCM	1095	AX8ZD
979	DK1UJ	1037	AX8DI	1096	AX8ZY
980	H83AVN	1038	CG8GS	1097	AX8JH
981	VE1AM	1039	W4QAW	1098	VU2IAZ
982	K2ZHA	1040	SV1QE	1099	AX8BG
983	LA2CE	1041	AX8GV	1100	G1UTR
984	WS2VZ	1042	VP8GE	1101	JA1TCH
985	GW4NZ	1043	W2ANX	1102	AX8AT
986	K8PET	1044	CM8VEY	1103	AX8F
987	Z8B8P	1045	ZM1FV	1104	F8MS
988	AX8JB	1046	W8E8J	1105	W8E8P
989	VO1TB	1047	W4EM	1106	K8AI
990	AX8FT	1048	JA8CLA	1107	E2W8
991	JA1KXN	1049	W1F3J	1108	ZM1AMM
992	VO1BD	1050	JH1MTB	1109	AX8AFH
993	W8TAX	1051	VE8RME	1110	WB8O
994	SM8BEC	1052	ZL1AAP	1111	ZL1RGC
995	SM8CKB	1053	VE8AYM	1112	CR7G
996	K8UT/	1054	W8LL	1113	VP7H
997	W8WNB	1055	AX8FD	1114	AX8RAX
998	W8CPZ	1056	AX8EX	1115	W7UOI
999	W8WNB	1057	AX8EX	1116	AX8FK
1000	AX8GM	1058	AX8BC	1117	AX8D
1001	AX8AGI	1059	W8AIZ	1118	AX8GC
1002	Z8GK	1060	AX8GD	1119	G3RR
1003	AX8NT	1061	AX8CP	1120	AX8PV
1004	W8VPR	1062	AX8LH	1121	AX8BY
1005	W8NAZ	1063	ZL1BHM	1122	ZM1AVS
1006	Z8B8K	1064	VE8BNC	1123	WB8POD
1007	IL8P	1065	W8BAH	1124	AX8D
1008	W8JXK	1066	118SU	1125	Z86GP
1009	AX8BM	1067	AX8KS	1126	W8VJZ
1010	K7YWZ	1068	AX8DF	1127	W8EAV
1011	K4BZF	1069	K8BWT	1128	D16NP
1012	V1KZ	1070	AX8AG	1129	AX8VB
1013	W8GCU	1071	Y8BAE	1130	98LH
1014	AX8AJR	1072	U8HJ	1131	D1MD
1015	AX8TF	1073	U8MI	1132	AX8VC
1016	AX8BM	1074	JA8FT	1133	W8PZ
1017	CG8WS	1075	U8PG	1134	D1AC
1018	HK4TA	1076	U8W	1135	ZM1AZX
1019	K8LKL	1077	U8W	1136	W8LC
1020	ZM1ABW	1078	U8W	1137	W8P
1021	K8LKL	1079	U8W	1138	AX8UC
1022	VE8H	1080	U8W	1139	AX8AF
1023	V8RNEZ	1081	U8W	1140	JA8GX
1024	D7M1	1082	AX8RX	1141	CG8K
1025	Y8AAN	1083	VE1TO	1142	AX8BAS
1026	AX8WD	1084	ZM2AVY	1143	W8K
1027	AX8PG	1085	W8SUA	1144	AX8AS
1028	W8HO	1086	E8HJX	1145	Y8AAO
1029	JA8ED	1087	E8HJX	1146	JA8REK
1030	Z8ILJ	1088	ZL1AUP	1147	JA8AWTG
		1089	VE8AD	1148	GL8C

V.H.F./U.H.F. SECTION

The following additional stations have qualified for the Award:

Cert. No.	Call	Cert. No.	Call	Cert. No.	Call
7	AX8ZP	11	AX8ZL	16	AX8ZJ
8	AX8YF	12	AX8ZM	17	AX8ZNG
9	AX8IO	13	AX8ZS	18	AX8PC
10	AX8ZB	14	AX8ZQ	19	AX8ZA
		15	AX8ZWL		

— . . . —

W.I.A. V.H.F.C.C.

Amateur:

Cert. No.	Call	Confirmations
48	VK3ZJ	250
47	VK3ZJ	266

— . . . —

W.I.A. 52 MHz. W.A.S. AWARD

New Members:

Cert. No.	Call	Additional Courses
90	VK4ZB	2
91	VK4AUN	1

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CASLON 401

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Price \$23.50



CASLON 601 and 602

A unique desk/table calendar clock, combining utility and beauty, receiving the Mainichi Industrial Design Award, Japan. Digital flip cards advance date, day, hour and minute automatically. 12- and 24-hour types. Anodized aluminum case houses built-in neon lamp. 601: 8.2 x 4.0 x 3.5 in. 602: 8.5 x 4.0 x 3.5 in.

Price \$24.50



CASLON 701

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Another supply of YAESU MUSEN FT-280 Transceivers arriving soon, with a power supply kit of Australian made components, 225-A & B Melbourne transformer of extra heavy duty special design, punched chassis, but no case or speaker included, for only \$399 the package. Hurry, prices are going up now everywhere. FT-280s as usual corrected for CW key-clicks. Further YAESU Units:-

FL-DX-2000 Linear Amplifier	\$225
FL-DX-400 Transmitter with table microphone	\$375
FL-2000-B Linear Amplifier with American CETRON 572-Ba	\$390
American CETRON 572-Ba	\$45
FC-8 or FC-2 Solid State Converters for 6 or 2 metres, 9V, 12, 25-30 MHz.	\$25
500 Hz. CW Mechanical Filters, Kokusai, as used in the FR-DX-400	\$20
KATSUAMI ELECTRONIC KEYS, Model EK26, for 240V. AC, switching 105V, bias or 500 mA. HT, with built-in monitor and keying paddle, fully automatic or semi-automatic as with a bug	\$60

ADDITIONALS:

Hy-Gain Hy-Quad, tri-band cubical quad, 10-15-20 metres with gamma matches for single co-ax feed, 1 KW. power	\$130
Hy-Gain TH60XX	\$220
Package deal: TH60XX with CDR Ham-M Rotator and 50 yards of 5-core rotator cable	\$400
Hy-Gain 14-AVO Vertical	\$62
Neutronics 4-BTV Vertical	\$60
Mosley TA-3JR, still only	\$105
Expected soon, the Mosley MUSTANG, 3 el. tri-band beam, 1 KW. capacity, equivalent of the Hy-Gain TH60XX	\$130
Webster and Mark Mobile Whips and Mounts as advertised before.	
OMEGA Noise Bridges, Model TE-7-01, still only \$25—although they now cost U.S. \$29.95 at the factory in Texas!	
FT-341 CRYSTALS, all channels 0 to 79, 375 to 515 KHz. in stock. Sorry, no other crystal frequencies.	
BALLUNS, 52 to 75 ohms, duplicates of the Hy-Gain BN-86, now with free co-ax plug!	\$12.50

MIDLAND PRODUCTS:

Type 13-719 One watt Transceivers, now on 27.240 or 27.880 MHz., also crystals for 27.085 MHz. available. Three channels, call signal, excellent for CW operation, with eight penlite batteries, earphone, carrying case, audio squelch control, battery voltage meter, each still only	\$37.50
Type 23-1358 Field Strength Meter, with five ranges tuneable from 1 to 300 MHz., with telescoping whip	\$10
Type 23-135 SWR-Power Meter, dual meters (100 micro-amp.) very sensitive for low power but good for 1 KW. maximum up to 175 MHz., reads forward and reflected power simultaneously, 52 ohm impedance	\$20
Type 23-128 SWR Meter, standard single meter type, 52 ohm impedance, with whip for field strength metering	\$12
PIT Dynamic Hand Microphone, steel case, 50K impedance, excellent voice quality, no rocking armature type, with coiled cord and mobile use clip	\$10
Table Model Dynamic Microphone, with PIT bar or lock switch, 50K impedance, a quality bargain at	\$15
Same Table Microphone with built-in two-stage pre-amplifier, adjustable for up to 50 dB. amplification	\$25
Co-ax Connectors: Midland types PL-259, SO-239 females with or without flanges, PL-258 double-ended female per connector	\$0.75
Co-ax. Inserts for PL-259 for thinner co-ax. cable	\$0.23
Expected soon, Midland 5 watt Base Station Transceivers, eight channels, 240V AC, built P.M.G. approved for 27.880 MHz. operation, with 5 meter and power output metering, including PIT microphone, with switch to be used as 3 watt public address amplifier into separate speaker(s). Target price, all inclusive, only \$100.	

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3-08	3/4	8	3	No. 3010	\$1.06
3-16	3/4	16	3	No. 3011	\$1.06
4-08	1	8	3	No. 3014	\$1.19
0-18	1	16	3	No. 3015	\$1.19
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References: A.R.P.L. Handbook, 1981;
"OST," March, 1959;
"Amateur Radio," Dec. 1959.

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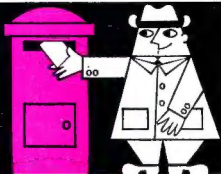
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